

# GRAVITATIONAL WAVE ANALYSIS WITH PULSAR TIMING ARRAYS

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# OUTLINE

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- Introduction
- Bayesian statistics
- Estimating signal parameters
- Detection significance
- Astrophysical inference

*\* glossary terms*

# GRAVITATIONAL WAVE SPECTRUM

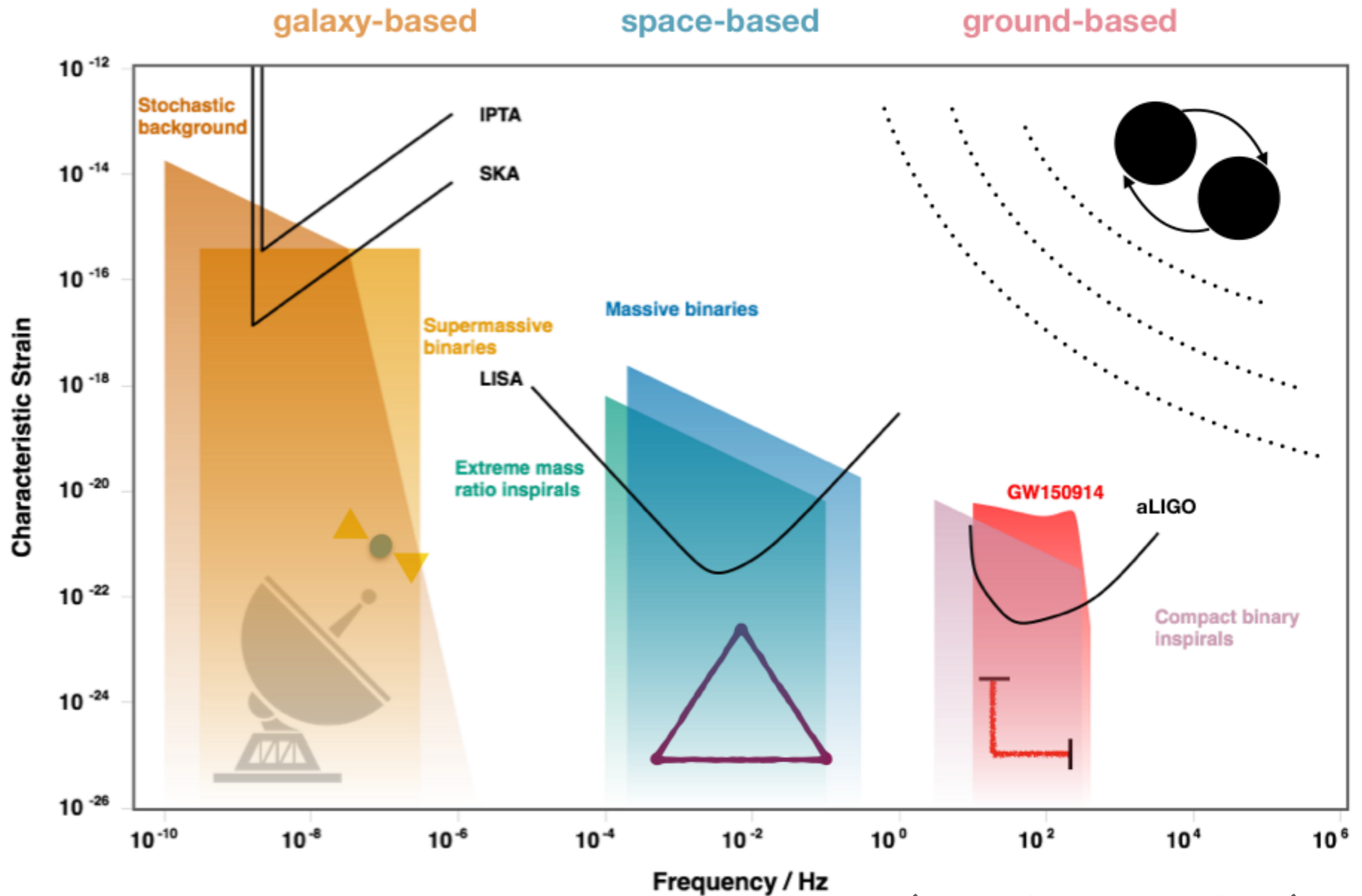


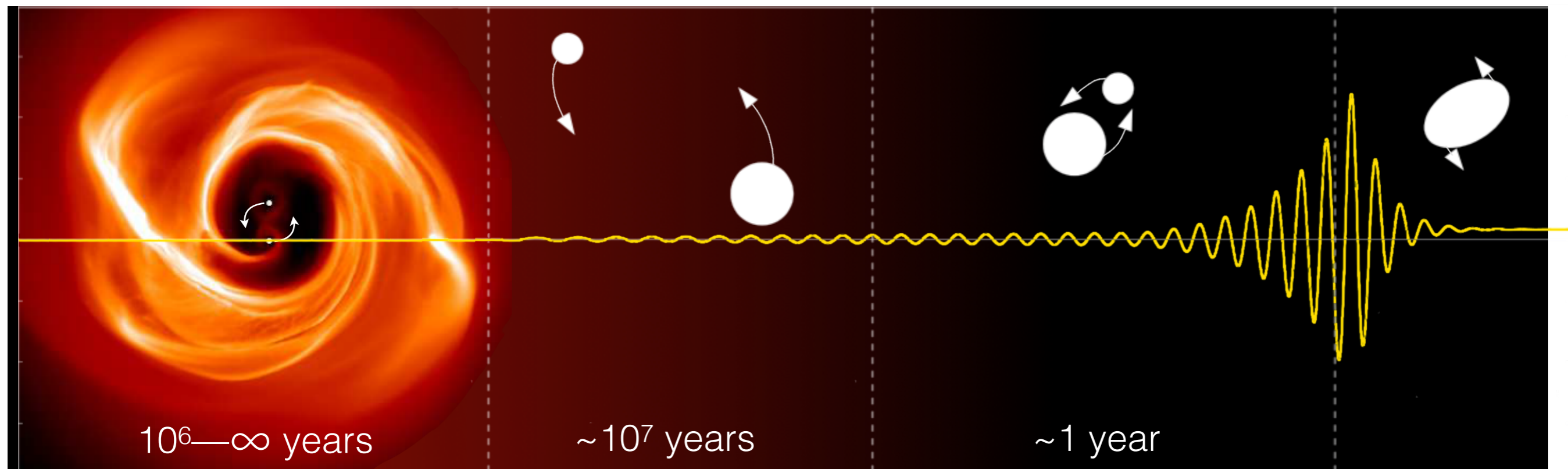
Figure: C.Berry + C. Mingarelli

# SUPERMASSIVE BLACK HOLE BINARIES

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- Pulsar timing arrays like NANOGrav are sensitive to nanohertz gravitational waves from supermassive black hole binaries
- These binaries are thought to form in the center of merging galaxies

*Figure: S. Burke-Spolaor*



# SIGNATURE OF VARIOUS SIGNALS

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- Signals can be classified into two distinct types:
  - **Stochastic** - Described through statistical properties; GW power proportional to variance of signal
  - **Deterministic** - A resolvable waveform we can characterize with typical properties, i.e., amplitude, frequency, phase, etc.

# TWO SCHOOLS OF THOUGHT ON HANDLING UNCERTAINTY

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Say an astronomer estimates the mass of a neutron star to be

*“ $M = (1.39 \pm .02) M_{\odot}$  with 90% confidence.”*

## FREQUENTIST

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The long-term frequency of with which you measure the neutron star mass to be in  $\{[M - 0.2, M + 0.2] M_{\odot}\}$  for any measured mass value  $M$  is 90%

## BAYESIAN

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You are 90% confident the true neutron star mass lies within  $[1.37 M_{\odot} - 1.41 M_{\odot}]$

# FREQUENTIST

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- Probability means long-term relative frequency
- You assume measured data is random, but the parameters of the governing hypothesis are fixed but unknown
- Construct a statistic to determine when data are consistent with model
- Probability distribution of statistic
- p-values and confidence intervals

# BAYESIAN

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- Probability means degree of belief
- The data are fixed, and the parameters of the governing hypothesis are random and mostly unknown
- Prior knowledge is incorporated
- Bayes theorem updates prior in light of additional data
- credible sets and odds ratios

# BAYES' THEOREM

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$$p(A, B) = p(A)p(B|A) = p(B)p(A|B)$$

*“probability that  $A$  is true  
given circumstances  $B$ ”*

*“probability that  $B$  is true  
given circumstances  $A$ ”*

*“probability that  $A$  is true without consideration of  $B$ ”*

$$\therefore p(B|A) = \frac{p(A|B)p(A)}{p(B)}$$

# USING BAYES' THEOREM: AN EXAMPLE

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*A test for a disease is 99% accurate.*



$$p(\text{positive}|\text{infected}) = 0.99$$

*1 in 10,000 people have the disease.*



$$p(\text{infected}) = 0.0001$$

*What is the probability you get a positive result but aren't infected?*



$$p(\text{infected}|\text{positive}) = ?$$

$$\begin{aligned} p(\text{infected}|\text{positive}) &= \frac{p(\text{positive}|\text{infected})p(\text{infected})}{p(\text{positive})} \\ &= \frac{0.99 \times 0.0001}{0.99 \times 0.0001 + 0.01 \times (1 - 0.0001)} \\ &\sim 1\% \end{aligned}$$

# LIKELIHOOD, PRIOR, POSTERIOR AND EVIDENCE

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$\vec{d}$  = parameters we know well

$\vec{\theta}$  = parameters we want to know more about

$$p(\vec{\theta}|\vec{d}) = \frac{p(\vec{d}|\vec{\theta})p(\vec{\theta})}{p(\vec{d})}$$

Terminology :

- $p(\vec{\theta}|\vec{d})$  : *posterior* probability
- $p(\vec{d}|\vec{\theta})$  : *likelihood*
- $p(\vec{\theta})$  : *prior* knowledge
- $p(\vec{d})$  : *evidence* ← difficult to compute!

# MODELING NOISE IN OUR DATA (INCLUDING GWS!)

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$$\delta t = M\epsilon + \mathbf{n}_{\text{white}} + \mathbf{n}_{\text{red}}$$

## *Timing model*

- *spin*
- *spin-down*
- *orbital parameters*
- *dispersion from ISM*

## *White noise*

- *uncorrelated in time*
- *instrumental*
  - \* *EFAC*
  - \* *EQUAD*
  - \* *ECORR*

## *“Red” noise*



- *correlated in time*
- *Primarily astrophysical*
  - *Intrinsic to pulsar*
  - *time-varying DM*
  - *GWs!*

# STOCHASTIC BACKGROUND – RED NOISE

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- Superposition of gravitational waves from a population of inspiraling supermassive black hole binaries
- Let's try a Fourier analysis of the background:

$$\mathbf{n}_{\text{red}} = F_{\text{red}} \mathbf{a}$$

*Fourier basis (sines and cosines)*  *Fourier coefficients* 

- We expect largest Fourier coefficients at lower gravitational wave frequencies; we write the red noise power as

$$P_{\text{red}}(f) = A f^{-\gamma}$$

# STOCHASTIC BACKGROUND – OBTAINING THE POSTERIOR

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*Marginalized Likelihood:*

$$p(\vec{\theta}, \varphi, \mathbf{a}|\delta t) = p(\delta t|\vec{\theta}, \mathbf{a})p(\mathbf{a}|\varphi)p(\varphi)p(\vec{\theta})$$

*Assume multivariate Gaussian priors and integrate over Fourier coefficients:*

$$p(\theta, \varphi|\delta t) \propto \frac{\exp\left(-\frac{1}{2}\delta\mathbf{t}^T C^{-1}\delta\mathbf{t}\right)}{\sqrt{\det(2\pi C)}}$$

*with Covariance Matrix:*

$$C = N + F_{\text{red}}\varphi F_{\text{red}}^T$$

*including correlated red noise power with elements for pulsar pairs (a,b) and frequencies (k,l):*



$$\varphi_{(ak),(bl)} = \Gamma_{ab}\rho_k\delta_{kl} + \kappa_{ak}\delta_{ab}\delta_{kl}$$

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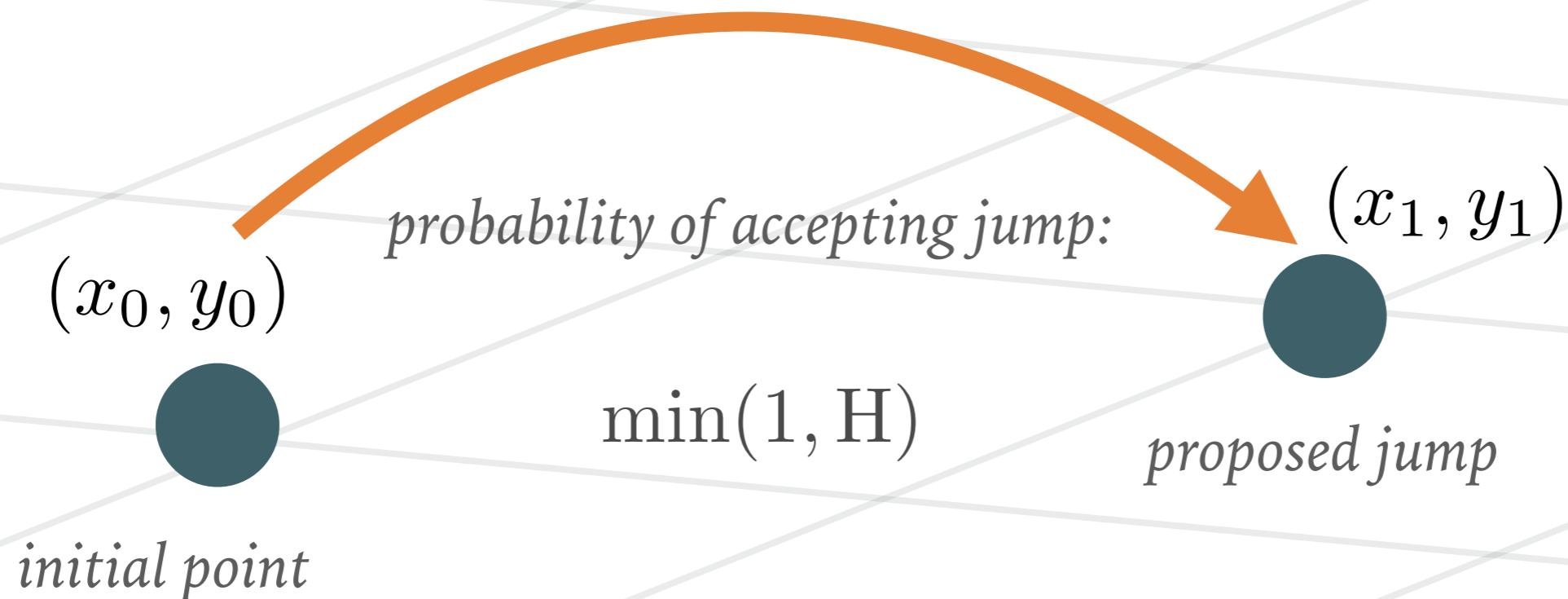
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# HOW WE SEARCH FOR IT

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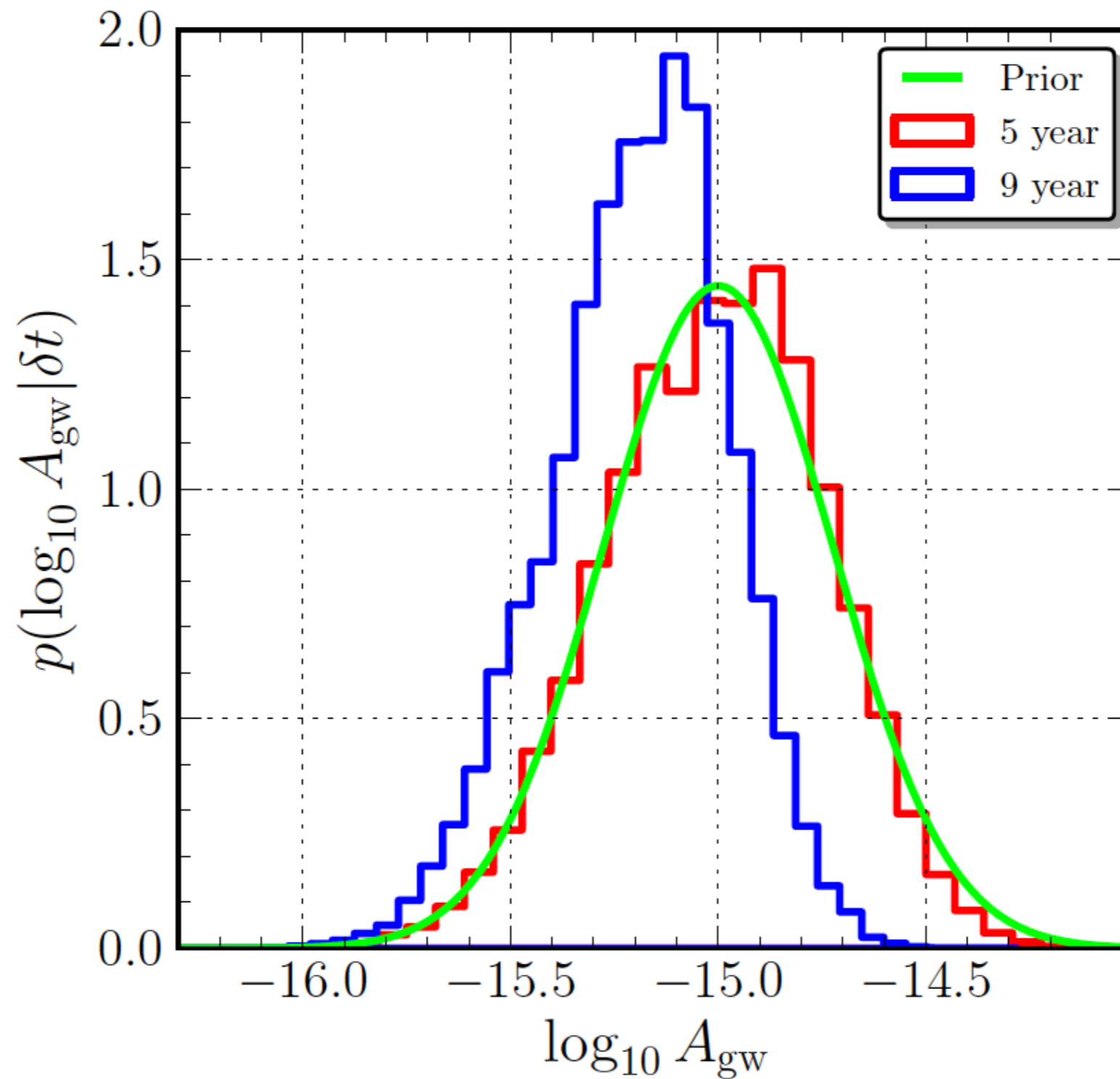
- Use a **Markov-chain Monte-Carlo (MCMC)** to efficiently generate samples from the posterior probability distribution that does not require computations of the evidence



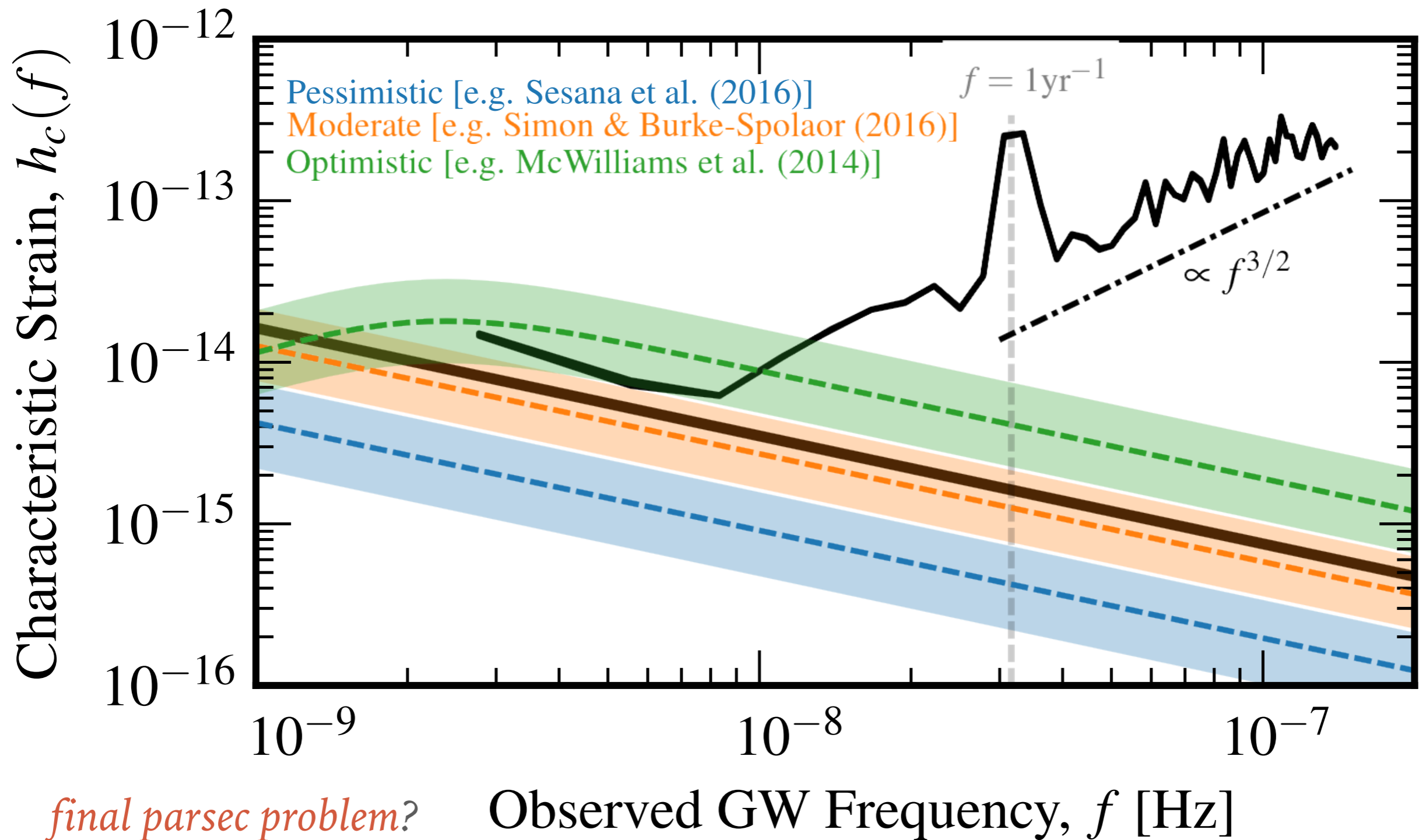
$$H \propto \frac{p(x_1, y_1 | \vec{d})}{p(x_0, y_0 | \vec{d})}$$

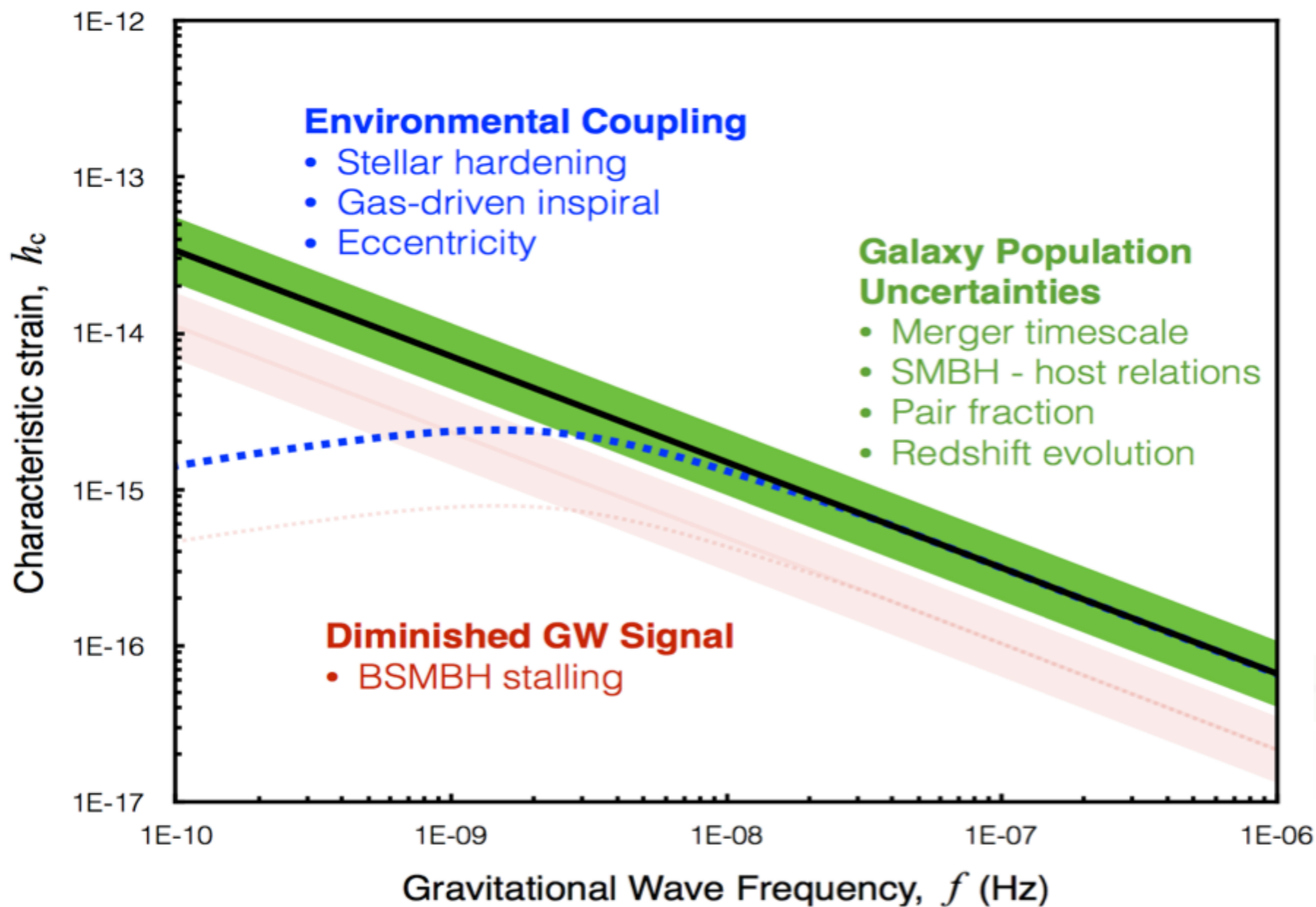
# WHAT WE GET – POSTERIOR DISTRIBUTIONS OF SIGNAL PARAMETERS

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# SENSITIVITY VERSUS MODELS

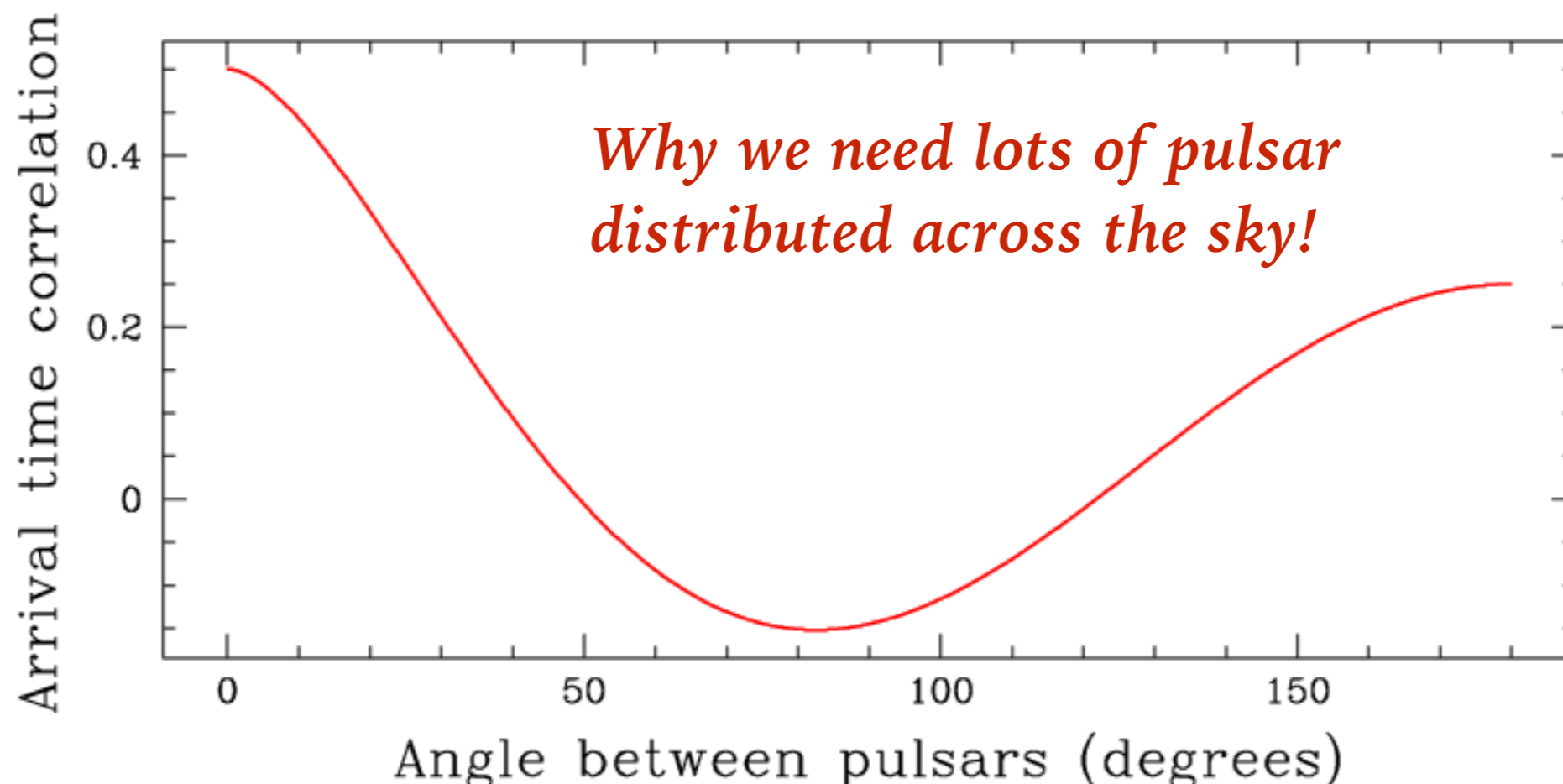




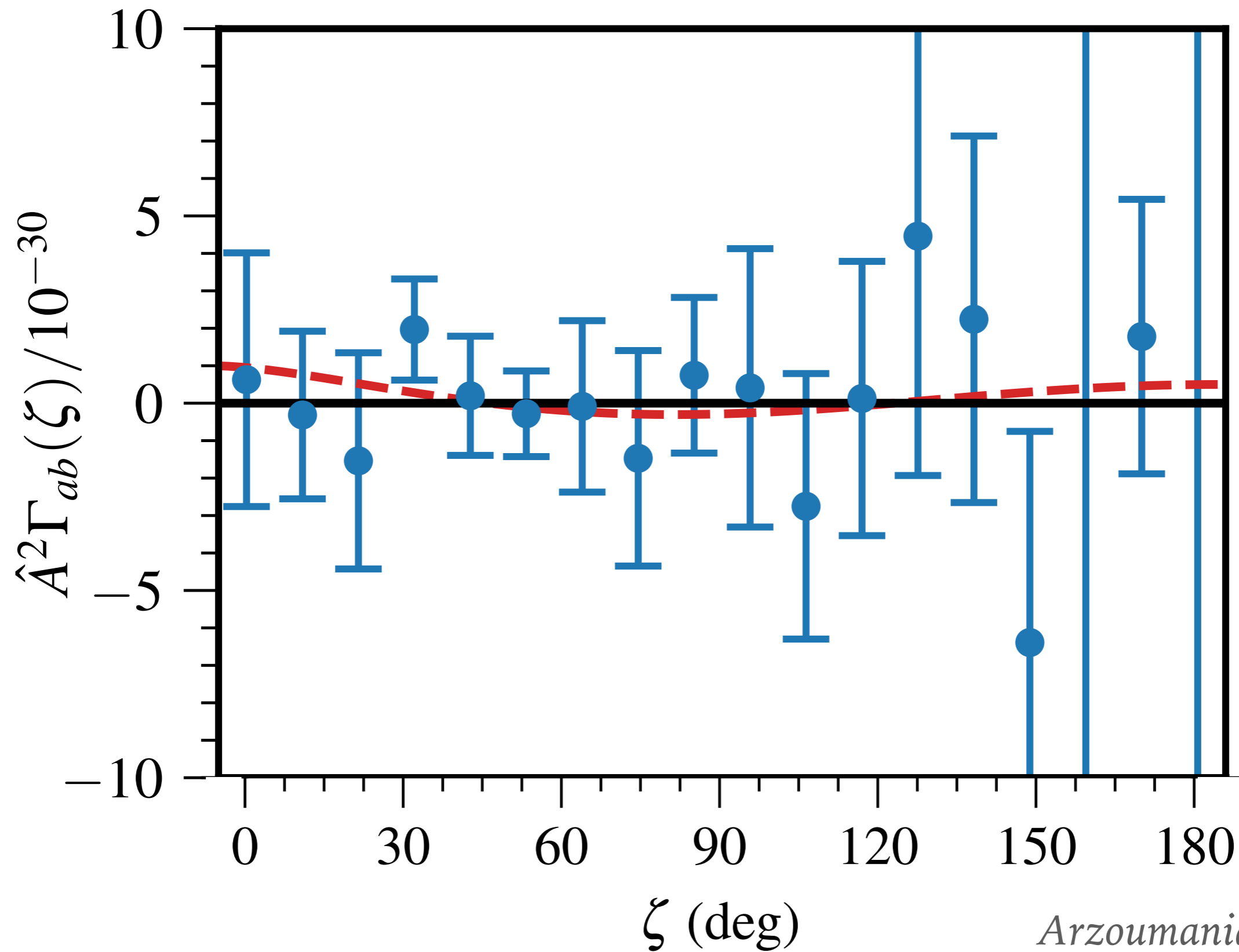
# HOW WE SEARCH FOR IT – RED NOISE + $\Gamma$

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- In addition to searching for the signal variance to get the power of the background, we also look for spatial correlations of the background power across our pulsar array
- Relation between arrival time correlation and angles between pulsar pairs is the **Hellings and Downs Curve**



# 11-YEAR RESULTS — H&D CORRELATIONS



Arzoumanian + 2018

# BEYOND PARAMETER ESTIMATION

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- Detection is essentially a model selection problem
- Comparing posteriors can give us an odds ratio (e.g. “2:1”)

$\mathcal{H}_1 \equiv$  “red-noise process like a *GWB with H&D correlations*”

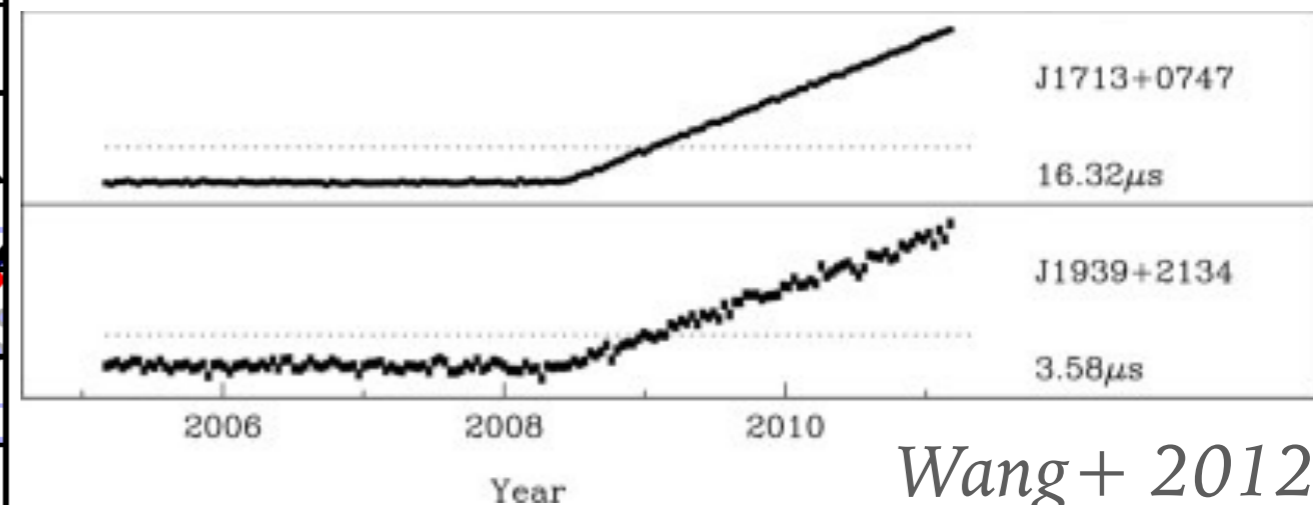
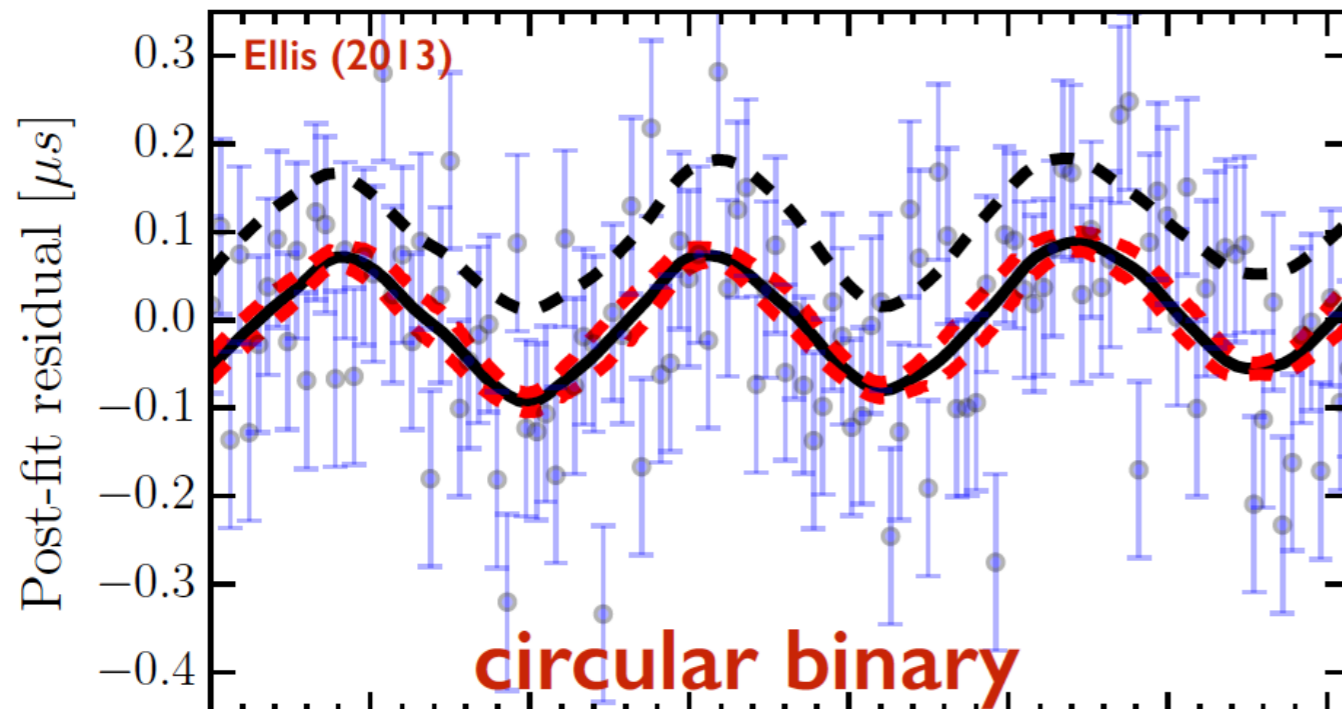
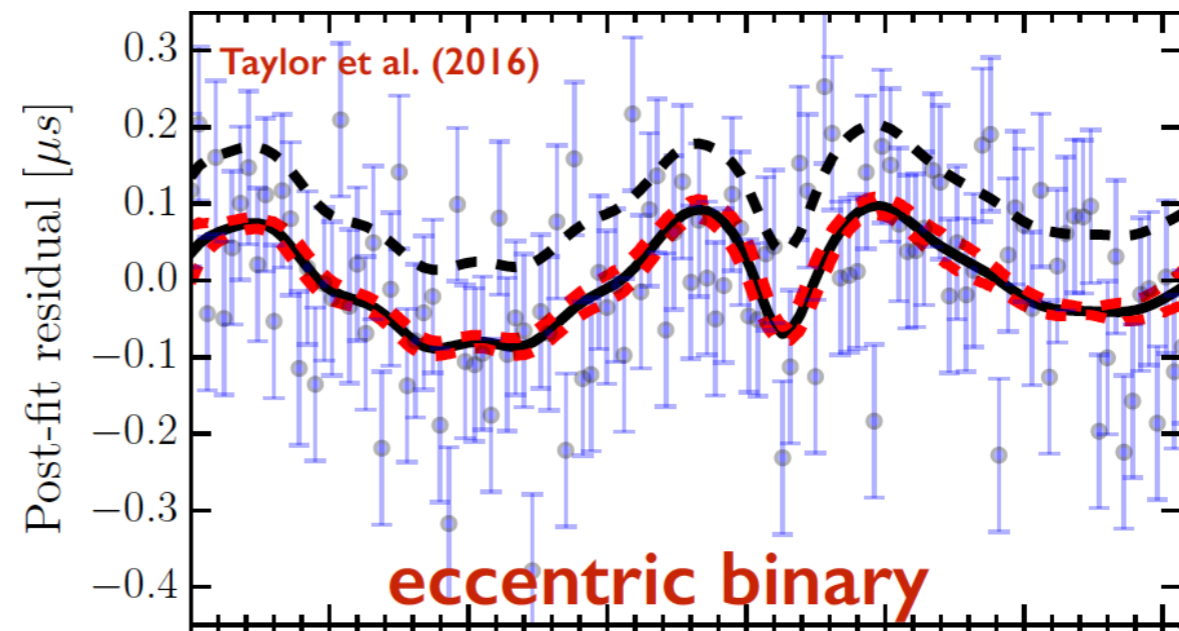
$\mathcal{H}_2 \equiv$  “red-noise process like a *GWB without H&D correlations*”

$$\mathcal{P}_{12} = \frac{p(\mathcal{H}_1|\mathbf{d})}{p(\mathcal{H}_2|\mathbf{d})} = \frac{p(\mathbf{d}|\mathcal{H}_1)}{p(\mathbf{d}|\mathcal{H}_2)} \frac{p(\mathcal{H}_1)}{p(\mathcal{H}_2)}$$

*posterior odds ratio      Bayes Factor      prior odds ratio*

# INDIVIDUAL SOURCES

- Circular Orbit - “continuous waves”
- Eccentric Orbit
- Burst with Memory



burst with memory

Wang + 2012

# CONTINUOUS WAVES

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- **MCMC** searches for a GW signal with specific amplitude, frequency and phase

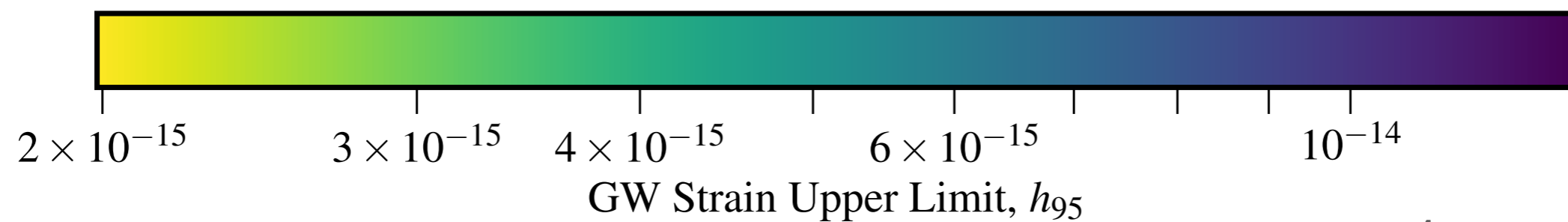
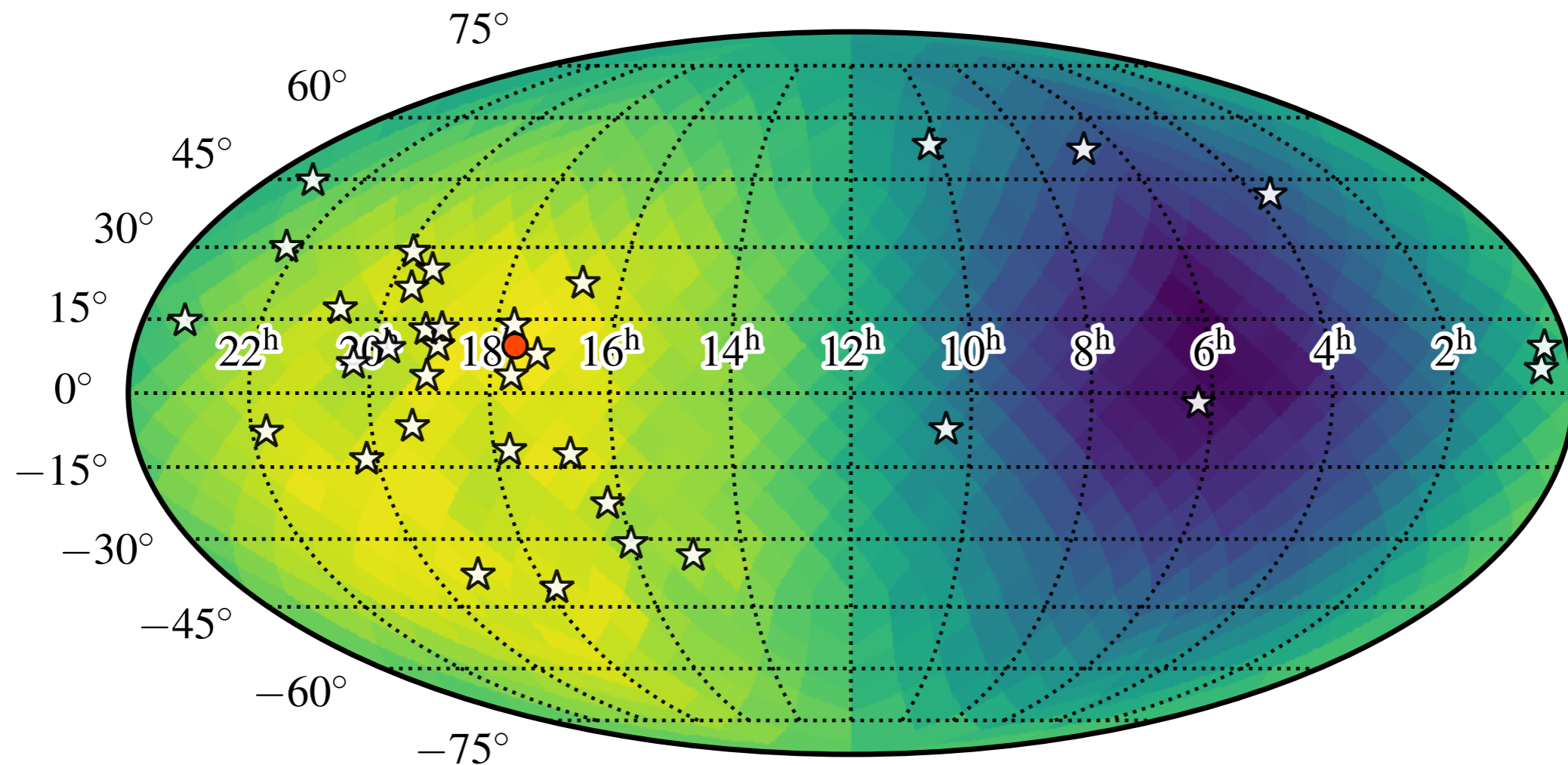
$$h(t) = h_0 \cos(ft + \Psi)$$

- Our model includes parameters:

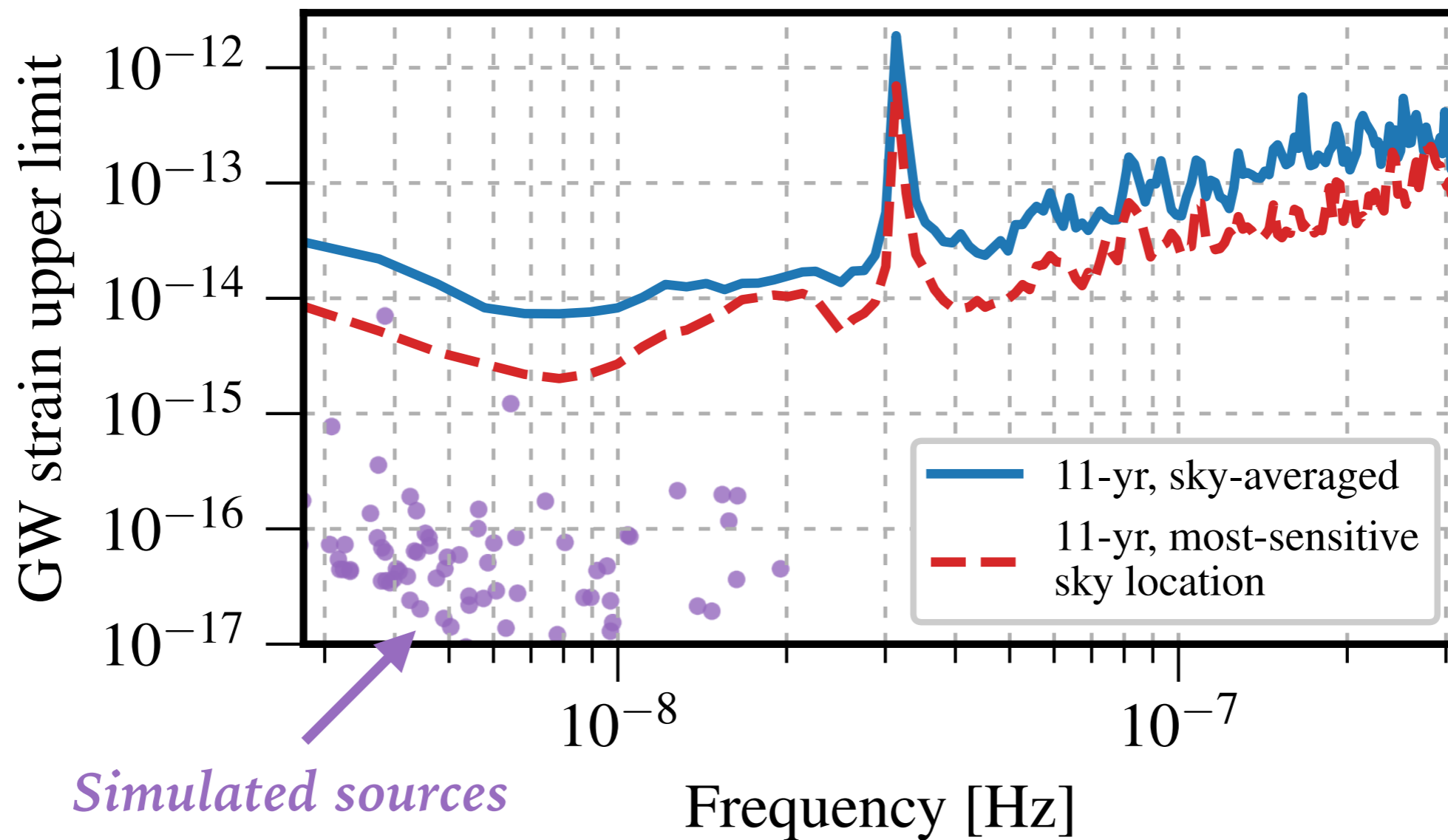
$$\theta, \phi, \Psi_0, \psi, \mathcal{M}, f, h_0$$

- By searching for specific sources we can place limits that are interesting to astronomers!

# ANGULAR SENSITIVITY



# SENSITIVITY PER GW FREQUENCY



# UNIQUE CHALLENGES & OPPORTUNITIES

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- We presume the stochastic background is always in our data, hence we cannot “subtract” out the noise to isolate the signal - everything is modeled simultaneously in our MCMCs
- Volume of data necessitates super computing clusters and clever linear algebra to avoid expensive likelihood computations (some combinations of frequentist and bayesian methods)
- Timescales needed for pulsar timing analysis are on the order of other astrophysical phenomena - mistaken identities
  - \* forays into solar cycles, planetary science, dark matter, etc.

# SUMMARY

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- PTA data analysis uses Bayesian inference to make strong statements given our data set
- Stochastic and deterministic searches underway to extract information about the presence and character of GW signals from supermassive black hole binaries
- Our limits are ruling out different astrophysical models — constraining our knowledge of how these binaries form and evolve
- pulsar astronomy + general relativity + astrophysics =

*FUN!*

